### Constrained Existence Problem for Weak Subgame Perfect Equilibria with $\omega$ -regular Boolean Objectives

Thomas Brihaye Véronique Bruyère Aline Goeminne Jean-François Raskin



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Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works

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# Theoretical background and studied problem

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#### Boolean games



- G = (V, E): a finite directed graph;
- Π: a finite set of players;
- (V<sub>i</sub>)<sub>i∈Π</sub>: a partition of V between the players;
- for each  $i \in \Pi$ , Gain<sub>i</sub> :  $V^{\omega} \rightarrow \{0, 1\}$ : gain function;
- initialized game  $(\mathcal{G}, v_0)$ .

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#### Plays and histories



- play ρ: infinite path in G from v<sub>0</sub>;
   Ex : v<sub>0</sub>v<sub>1</sub>v<sub>2</sub>v<sub>3</sub><sup>ω</sup>
- history h: finite path in G from v<sub>0</sub>; Ex: v<sub>0</sub>v<sub>1</sub>

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Objectives (1/2)

#### Given a play, how to define the gain of a player ?

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- Each player  $i \in \Pi$  has an  $\omega$ -regular objective charaterized by Win<sub>i</sub>  $\subseteq V^{\omega}$ .
- Gain<sub>i</sub>( $\rho$ ) = 1 if and only if  $\rho \in Win_i$ .

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- Gain<sub>i</sub>( $\rho$ ) = 1 if and only if  $\rho \in Win_i$ .

Classical  $\omega$ -regular objectives: Büchi, co-Büchi, Explicit Muller, Muller, Parity, Streett and Rabin.

Rem:

- prefix-independent objectives;
- all players have the same type of objective (ex: each player has a Büchi objective).

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## Objectives (2/2)

Example



#### Game with Büchi objectives:

• 
$$P_{\bigcirc}$$
: { $v_1$ };  
•  $P_{\square}$ : { $v_3, v_5$ };

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## Objectives (2/2)

Example



#### Game with Büchi objectives:

- *P*<sub>O</sub>: {*v*<sub>1</sub>};
- $P_{\Box}$ : { $v_3, v_5$ };

Play 
$$\rho = v_0 v_1 v_2 v_3^{\omega}$$
:  
Gain<sub>( $\rho$ ) = 0  
Gain<sub>( $\rho$ ) = 1.</sub></sub>

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## Strategies (1/2)

A strategy can be associated with each player  $i \in \Pi$ :  $\sigma_i$ : Hist<sub>i</sub>( $v_0$ )  $\rightarrow V$ .



σ<sub>○</sub>: memoryless strategy of player P<sub>○</sub>;
 σ<sub>□</sub>: memoryless strategy of player P<sub>□</sub>;

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   σ<sub>□</sub>: memoryless strategy of player P<sub>□</sub>;
   (σ<sub>○</sub>,σ<sub>□</sub>) is a *strategy profile*, denoted by σ;
- outcome:  $\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{v_0} = v_0 v_1 v_2 v_3^{\omega}$ .

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Strategies (2/2)

Finitely deviating strategy



#### Finitely deviating strategy

Let  $\sigma_i$  and  $\sigma'_i$  be two strategies,  $\sigma'_i$  is *finitely deviating* from  $\sigma_i$  if  $\sigma'_i$  and  $\sigma_i$  differ only on a finite number of histories.

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Finitely deviating

Not finitely deviating

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Strategies (2/2)

Finitely deviating strategy

**Example:**  $\sigma'_{\Box}$  differs from  $\sigma_{\Box}$  only on the history  $v_0$ :  $\sigma'_{\Box}(v_0) = v_4$  and  $\sigma_{\Box}(v_0) = v_1.$  $v_0$  $v_1$ V4 V6  $V_2$ 

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Strategies (2/2)

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## Subgame

Let  $hv \in \text{Hist}(v_0)$  be a history, the game  $(\mathcal{G}_{|h}, v)$  called *subgame* of  $(\mathcal{G}, v_0)$  is the same game played after hv:

Gain<sub>\[h</sub>(\rho) = Gain(h\rho);  
if 
$$\overline{\sigma} \to \overline{\sigma}_{\[h]h}$$
 such that  
 $h' \in \operatorname{Hist}(v): \overline{\sigma}_{\[h]h}(h') = \overline{\sigma}(hh')$ 



#### Nash Equilibrium

Let  $\overline{\sigma}$  be a strategy profile,  $\overline{\sigma}$  is a  $(\mathcal{G}, v_0)$ , if for all  $i \in \Pi$  and  $\sigma'_i$ 

Nash equilibrium ( NE) in

$$\mathsf{Gain}_i(\langle \overline{\sigma} 
angle_{\mathsf{v}_0}) \geq \mathsf{Gain}_i(\langle \sigma'_i, \sigma_{-i} 
angle_{\mathsf{v}_0}).$$

Rem: no

profitable deviation

#### (Weak) Nash Equilibrium

Let  $\overline{\sigma}$  be a strategy profile,  $\overline{\sigma}$  is a weak Nash equilibrium (weak NE) in  $(\mathcal{G}, v_0)$ , if for all  $i \in \Pi$  and  $\sigma'_i$  finitely deviating from  $\sigma_i$ :

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subgame perfect equilibrium

Let  $\overline{\sigma}$  be a strategy profile,  $\overline{\sigma}$  is a subgame perfect equilibrium ( SPE) in  $(\mathcal{G}, v_0)$ , if for all  $hv \in \text{Hist}(v_0)$ :  $\overline{\sigma}_{\restriction h}$  is a NE in  $(\mathcal{G}_{\restriction h}, v)$ .

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Let  $\overline{\sigma}$  be a strategy profile,  $\overline{\sigma}$  is a weak subgame perfect equilibrium (weak SPE) in  $(\mathcal{G}, v_0)$ , if for all  $hv \in \text{Hist}(v_0)$ :  $\overline{\sigma}_{\upharpoonright h}$  is a weak NE in  $(\mathcal{G}_{\upharpoonright h}, v)$ .

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Notions of weak NE/SPE already introduced and studied in [BBMR15] and [BRPR17].

Theoretical	background	and	studied	problem
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Reachability and safety □

Conclusion and future works

## NE, SPE, weak NE and weak SPE (2/2) Example



• 
$$\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{v_0} = v_0 v_1 v_2 v_3^{\omega}$$
: Gain = (0, 1);

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## NE, SPE, weak NE and weak SPE (2/2) $_{\rm Example}$



•  $\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{v_0} = v_0 v_1 v_2 v_3^{\omega}$ : Gain = (0, 1); • profitable deviation  $\sigma'_{\bigcirc}$  for  $P_{\bigcirc}$ ,  $\langle \sigma'_{\bigcirc}, \sigma_{\square} \rangle_{v_0} = v_0 (v_1 v_2)^{\omega}$ , Gain = (1, 0)

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only one way to improve his gain;

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- only one way to improve his gain;
- $\sigma'_{\bigcirc}$  not finitely deviating

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- only one way to improve his gain;
- $\sigma'_{\bigcirc}$  not finitely deviating  $\rightarrow$  weak NE.

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### Studied problem

#### Constraint problem

Let  $x, y \in \{0, 1\}^{|\Pi|}$  be two thresholds, decide if there exists a weak SPE  $\overline{\sigma}$  in  $(\mathcal{G}, v_0)$  such that  $x \leq \text{Gain}(\langle \overline{\sigma} \rangle_{v_0}) \leq y$ .

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	exp. Muller	Muller	co-Büchi	Parity	Streett	Rabin
P-complete	×					
NP-complete		×	×	×	×	×

Rem : Büchi is NP-easy.

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## Characterization

## (Good) Symbolic witness (1/2)

#### Symbolic witness $\mathcal{P}$

- A symbolic witness  $\mathcal{P}$  is:
  - a set of lassoes with a polynomial size representation,
  - there is a polynomial number of lassoes in *P*,



## (Good) Symbolic witness (1/2)

#### $\textbf{Good} \text{ Symbolic witness } \mathcal{P}$

A **good** symbolic witness  $\mathcal{P}$  is:

- a set of lassoes with a polynomial size representation,
- there is a polynomial number of lassoes in *P*,
- these lassoes have some "good" properties.



## (Good) Symbolic witness (2/2)

#### Theorem

Let  $(\mathcal{G}, v_0)$  be a Boolean game with prefix-independent gain functions. Are equivalent:

- **1** there exists a weak SPE in  $(\mathcal{G}, v_0)$  with payoff p;
- **2** there exists a symbolic witness  $\mathcal{P}$  that contains a lasso with payoff p;
- 3 there exists a weak SPE in  $(\mathcal{G}, v_0)$  with payoff p and finite memory in  $\mathcal{O}(|\Pi| \times |V|^3)$ .

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Folk theorem (1/2)
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**Main idea:** computation of the set of all possible payoffs of a weak SPE from a given vertex v:  $\mathbf{P}_{k^*}(v)$ .

#### Folk theorem

Let  $(\mathcal{G}, v_0)$  be a Boolean game with prefix-independent gain functions, there exists a weak SPE  $\overline{\sigma}$  with payoff p in  $(\mathcal{G}, v_0)$  if and only if  $\mathbf{P}_{k^*}(v) \neq \emptyset$  for all  $v \in \text{Succ}^*(v_0)$  and  $p \in \mathbf{P}_{k^*}(v_0)$ .
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### Folk theorem (2/2)

How to compute the sets  $\mathbf{P}_{k^*}(v)$ ?

### Folk theorem (2/2)

#### How to compute the sets $\mathbf{P}_{k^*}(v)$ ?

- <u>step 0</u>:begin with all the realizable payoffs from v, *i.e.*,  $p \in \mathbf{P}_0(v)$  iff  $\exists \rho$  beginning in v such that  $Gain(\rho) = p$ ;
- step k: remove some payoffs, from  $\mathbf{P}_k(v)$ , which can't be payoffs of a weak SPE and **adjust** the set  $\mathbf{P}_k(v')$  of the other vertices v';
- final step: reach a fixpoint  $\mathbf{P}_{k^*}(v)$ .

### Folk theorem (2/2)

#### How to compute the sets $\mathbf{P}_{k^*}(v)$ ?



Game with Büchi objectives:

Player  $\bigcirc$ : { $v_1$ };

• Player  $\Box$ : { $v_3$ ,  $v_5$ };

	v <sub>0</sub>	<i>v</i> <sub>1</sub>	<i>v</i> <sub>2</sub>	V <sub>3</sub>	<i>v</i> <sub>4</sub>	<i>V</i> 5	v <sub>6</sub>
<b>P</b> <sub>0</sub>	$\{(0,0),(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	{(0,1)}	$\{(0,0),(0,1)\}$	{(0,1)}	{(0,0)}
<b>P</b> <sub>1</sub>	{ <b>(0,0)</b> , (1,0), (0,1)}	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,0)\}$
<b>P</b> <sub>2</sub>	{ <b>(1,0)</b> , (0, 1)}	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,0)\}$
$\mathbf{P}_{k^*}$	$\{(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,0)\}$

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## **Reachability and safety**

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		Image: 1 minute of the second seco	

not prefix-independent objectives;

Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works
		<ul> <li>Image: A set of the set of the</li></ul>	

- not prefix-independent objectives;
- weak SPEs: PSPACE-complete for Reachability and Safety;

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  - **Reachability:** weak SPE  $\leftrightarrow$  SPE, PSPACE-complete;

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- **not** prefix-independent objectives;
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  - Reachability: weak SPE ↔ SPE, PSPACE-complete;
  - Safety: thanks to previous results [Umm05] and the structure of our proof,

Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works
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Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works

# **Conclusion and future works**

Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works

■ Existence of a good symbolic witness ↔ existence of a weak SPE;

Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works

- Existence of a good symbolic witness  $\leftrightarrow$  existence of a weak SPE;
- Existence of weak SPEs which need "small" memory;

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- Existence of a good symbolic witness  $\leftrightarrow$  existence of a weak SPE;
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**Complexity results:** 

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Complexity results: weak SPEs :

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- Existence of a good symbolic witness  $\leftrightarrow$  existence of a weak SPE;
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#### Complexity results: weak SPEs :

	Explicit Muller	Co-Büchi	Parity	Muller	Rabin	Streett	Reachability	Safety
P-complete	×							
NP-complete		×	×	×	×	×		
PSPACE-complete							×	×

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open for Büchi, NP-easyness is known;

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NP-complete		×	×	×	×	×		
PSPACE-complete							×	×

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#### SPEs:

Reachability and Safety : PSPACE-complete.

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#### Future works

- Exact complexity class for Boolean games with Büchi objectives;
- Constraint problem for games with quantitative gain functions;
  Extension to SPE;

...

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Thomas Brihaye, Véronique Bruyère, Noémie Meunier, and Jean-François Raskin.

Weak subgame perfect equilibria and their application to quantitative reachability.

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On the existence of weak subgame perfect equilibria.

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Rational Behaviour and Strategy Construction in Infinite Multiplayer Games.

Diploma thesis, RWTH Aachen, 2005.

#### Classical $\omega$ -regular winning condition

A play  $\rho = \rho_0 \rho_1 \rho_2 \dots$  satisfies one of the following winning conditions iff Reachability given  $F \subseteq V$ ,  $Occ(\rho) \cap F \neq \emptyset$ ; Safety given  $F \subseteq V$ ,  $Occ(\rho) \cap F = \emptyset$ ; Büchi given  $F \subseteq V$ ,  $Inf(\rho) \cap F \neq \emptyset$ ; **Co-Büchi** given  $F \subseteq V$ ,  $Inf(\rho) \cap F = \emptyset$ ; Parity  $\Omega: V \to \{1, \ldots, d\}$ , max(lnf( $\Omega(\rho)$ )) is even; Explicit Muller given  $\mathcal{F} \subseteq \mathcal{P}(V)$ ,  $Inf(\rho) \in \mathcal{F}$ ; Muller given a coloring function  $\Omega: V \to \{1, \ldots, d\}$ , and  $\mathcal{F} \subseteq \mathcal{P}(\Omega(V)), \operatorname{Inf}(\Omega(\rho)) \in \mathcal{F};$ Rabin given  $(G_i, R_i)_{1 \le i \le k}$  a family of pair of sets  $G_i, R_i \subseteq V$ , there exists  $j \in 1, \ldots, k$  such that  $lnf(\rho) \cap G_i \neq \emptyset$  and  $\operatorname{Inf}(\rho) \cap R_i = \emptyset;$ 

Streett given  $(G_j, R_j)_{1 \le j \le k}$  a family of pair of sets  $G_j, R_j \subseteq V$ , for all  $j \in 1, ..., k \ln f(\rho) \cap G_j = \emptyset$  or  $\ln f(\rho) \cap R_j \ne \emptyset$ .

Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works

### Symbolic witness

#### Symbolic witness

Let  $(\mathcal{G}, v_0)$  be an initialized Boolean game with prefix-independent gain functions. Let  $I \subseteq (\Pi \cup \{0\}) \times V$  be the set

$$I = \{(0, v_0)\} \cup \{(i, v') \mid \text{ there exists } (v, v') \in E\}$$

such that  $v, v' \in \text{Succ}^*(v_0)$  and  $v \in V_i$ .

A symbolic witness is a set  $\mathcal{P} = \{\rho_{i,v} \mid (i, v) \in I\}$  such that each  $\rho_{i,v} \in \mathcal{P}$  is a lasso of G with First $(\rho_{i,v}) = v$  and with length bounded by  $2 \cdot |V|^2$ .

A symbolic witness has thus at most  $|V| \cdot |\Pi| + 1$  lassoes (by definition of I) with polynomial length.

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### FPT

Intuitively, a language is in FPT if there is an algorithm running in polynomial time with respect to the input size times some computable function on the parameter.

Let  $\mathcal{G}$  be a Boolean game. The constraint problem is in FPT for Reachability, Safety, Büchi, co-Büchi, Parity, Muller, Rabin, and Streett objectives. The parameters are

- the number |∏| of players for Reachability, Safety, Büchi, co-Büchi, and Parity objectives,
- the number  $|\Pi|$  of players and the numbers  $k_i$ ,  $i \in \Pi$ , of pairs  $(G_j^i, R_j^i)_{1 \le j \le k_i}$ , for Rabin and Streett objectives, and
- the number |Π| of players, the numbers d<sub>i</sub>, i ∈ Π, of colors and the sizes |F<sub>i</sub>|, i ∈ Π, of the families of subsets of colors for Muller objectives.

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#### Good symbolic witness

A symbolic witness  $\mathcal{P}$  is *good* if for all  $\rho_{j,u}$ ,  $\rho_{i,v'} \in \mathcal{P}$ , for all vertices  $v \in \rho_{j,u}$  such that  $v \in V_i$  and  $v' \in \text{Succ}(v)$ , we have  $\text{Gain}_i(\rho_{j,u}) \geq \text{Gain}_i(\rho_{i,v'})$ .



Theoretical background and studied problem	Characterization	Reachability and safety	Conclusion and future works

## ${\small Symbolic\ witness}$

Example



)		$(0, v_0)$	(2, v <sub>4</sub> )	$(1, v_2)$	$(1, v_1)$	$(1, v_3)$	(2, v <sub>5</sub> )	(2, v <sub>6</sub> )	$(1, v_5)$	$(1, v_6)$
<i>'</i>	lasso	$v_0 v_1 v_2 v_3^{\omega}$	$v_4 v_5^{\omega}$	$v_2v_3^{\omega}$	$v_1v_2v_3^\omega$	$v_3^{\omega}$	$v_5^{\omega}$	$v_6^{\omega}$	$v_5^{\omega}$	$v_6^{\omega}$
	payoff	(0, 1)	(0, 1)	(0,1)	(0,1)	(0, 1)	(0, 1)	(0,0)	(0, 1)	(0,0)

	v <sub>0</sub>	<i>v</i> <sub>1</sub>	<i>v</i> <sub>2</sub>	V3	<i>v</i> <sub>4</sub>	<i>V</i> 5	V <sub>6</sub>
<b>P</b> <sub>0</sub>	$\{(0,0),(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	{ <b>(0,0)</b> , (0,1)}	$\{(0,1)\}$	{(0,0)}
<b>P</b> <sub>1</sub>	{ <b>(0,0)</b> , (1,0), (0,1)}	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	{(0,1)}	$\{(0,1)\}$	{(0,0)}
<b>P</b> <sub>2</sub>	{ <b>(1,0)</b> , (0,1)}	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,1)\}$	$\{(0,0)\}$
$\mathbf{P}_{k^*}$	$\{(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(1,0),(0,1)\}$	$\{(0,1)\}$	{(0,1)}	$\{(0,1)\}$	{(0,0)}

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(**Remove**) for all odd k: if there exists  $v \in V_i$  and there exists  $p \in \mathbf{P}_{k-1}(v)$  such that there exists  $v' \in \operatorname{Succ}(v)$  such that for all  $p' \in \mathbf{P}_{k-1}(v')$  we have:  $p_i < p'_i$ , then

$$\bullet \mathbf{P}_k(v) = \mathbf{P}_{k-1}(v) \setminus \{p\}$$

• for all 
$$u \neq v \mathbf{P}_k(u) = \mathbf{P}_{k-1}(u)$$
.

 ${}^1
ho = 
ho_0
ho_1
ho_2\dots$  is (p,k)-labeled if for all  $n\in\mathbb{N}$   $p\in\mathsf{P}_k(
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 $\exists \quad \mathbf{v} \leftarrow \{ \stackrel{\exists}{p}, \ldots \}$ 

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there exists a play (p, k - 1)-labeled <sup>1</sup> with payoff p from u.

yes: 
$$\mathbf{P}_k(u) = \mathbf{P}_{k-1}(u) \setminus \{p\};$$

• no:  $\mathbf{P}_k(u) = \mathbf{P}_{k-1}(u);$ 

• for all u such that  $p \notin \mathbf{P}_{k-1}(u) : \mathbf{P}_k(u) = \mathbf{P}_{k-1}(u) \setminus \{p\}$ .

 ${}^1
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