

Average conditions for permanence in nonautonomous competitive systems with nonlocal dispersal.

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Definitions and assumptions

By the nonautonomous competitive system of partial differential equations (PDEs) with dispersal we mean

$$\frac{\partial u_i}{\partial t} = \rho_i \left(\int_{\Omega} K_i(x, y) u_i(t, y) dy - u_i(t, x) \right) + f_i(t, x, u_1, \dots, u_N) u_i,$$
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- $f_i(t, x, u_1, \dots, u_N)$ – local per capita growth rate of the i -th species,
- $K(\cdot, \cdot)$ is nonlocal convolution kernel satisfying the following assumption

(A1) $K_i(\cdot, \cdot) : \bar{\Omega} \times \bar{\Omega} \rightarrow R$ are C^1 - functions, $\int_{\Omega} K_i(x, y) \leq 1$ for any $x \in \bar{\Omega}$, $\int_{\Omega} K_i(x, y) \neq 1$ and there is a $\delta_0 > 0$ such that for any $x \in \bar{\Omega}$, $K_i(x, y) > 0$ for $y \in \bar{\Omega}$ and $\|x - y\| < \delta_0$

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System (D) is the nonlocal dispersal counterpart of the following Kolmogorov competition system with random dispersal and Dirichlet boundary conditions

$$\begin{cases} \frac{\partial u_i}{\partial t} = \rho_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t \geq 0, x \in \Omega, \quad i = 1, \dots, N \\ u_i = 0 & x \in \partial\Omega \end{cases}$$

Denote by λ_i the principal eigenvalue of the problem

$$\begin{cases} \int_{\Omega} K_i(x, y) \varphi_i(y) dy - \varphi_i(x) = \lambda_i \varphi_i(x) & \text{on } \Omega \\ u_i = 0 & \text{on } \partial\Omega \end{cases}$$

Notice that principal eigenfunction φ_i corresponding λ_i can be chosen so that $\varphi_i(x) > 0$ for all $x \in \bar{\Omega}$. Throughout this paper we assume that $\lambda_i \geq 0$.

We deal with the positive solutions

Definition

The solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of system (D) is *positive* if $u_i(t, x) > 0$ for all $i = 1, \dots, N$, $t \in (0, \tau_{\max})$ and $x \in \Omega$.

Now we introduce a following assumptions for a function f_i

- (A2) $f_i : [0, \infty) \times \bar{\Omega} \times [0, \infty)^N \rightarrow \mathbb{R}$ ($1 \leq i \leq N$) as well as their first derivatives $\frac{\partial f_i}{\partial t}$ ($1 \leq i \leq N$), $\frac{\partial f_i}{\partial u_j}$ ($1 \leq i, j \leq N$), $\frac{\partial f_i}{\partial x_k}$ ($1 \leq k \leq n, 1 \leq i, j, \leq N$) are continuous. Moreover, the derivatives $\frac{\partial f_i}{\partial u_j}$ ($1 \leq i, j \leq N$) are bounded and uniformly continuous on sets of the form $[0, \infty) \times \bar{\Omega} \times B$ where B is a bounded subset of $[0, \infty)^N$.
- (A3) The functions $[[0, \infty) \times \bar{\Omega}] \ni (t, x) \mapsto f_i(t, x, 0, \dots, 0) \in \mathbb{R}$, $1 \leq i \leq N$ are bounded.

We write

$$\underline{a}_i = \inf \{ f_i(t, x, 0, \dots, 0) : t \geq 0, x \in \bar{\Omega} \}$$

$$\bar{a}_i = \sup \{ f_i(t, x, 0, \dots, 0) : t \geq 0, x \in \bar{\Omega} \}.$$

$$(A4) \quad \frac{\partial f_i}{\partial u_j}(t, x, u) \leq 0 \text{ for all } t \geq 0, x \in \bar{\Omega}, u \in [0, \infty)^N, \\ 1 \leq i, j, \leq N, i \neq j.$$

$\frac{\partial f_i}{\partial u_j}(t, x, u_1, \dots, u_N)$ measures the influence of the j th species on the growth rate of the i th species.

The systems which satisfy assumption (A4) we call *competitive*.

$$(A5) \quad \text{There exist } \underline{b}_{ii} > 0 \text{ such that } \frac{\partial f_i}{\partial u_i}(t, x, u) \leq -\underline{b}_{ii} \text{ for all } t \geq 0, \\ x \in \bar{\Omega}, 1 \leq i \leq N, u \in [0, \infty)^N.$$

Let $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$, $t \in [0, \tau_{\max})$ be a positive solution of (D).

For each $1 \leq i \leq N$ we define $\xi_i(t)$, $t \in [0, \infty)$ to be the positive solution of the ordinary differential equations

$$\begin{cases} \xi_i'(t) = (\rho_i \lambda_i + \max_{x \in \bar{\Omega}} f_i(t, x, 0, \dots, 0) - \underline{b}_{ii} \xi_i(t)) \xi_i(t) \\ \xi_i(0) = \sup_{x \in \bar{\Omega}} \frac{u_i(0, x)}{\varphi_i(x)} \end{cases} \quad (1)$$

Lemma 1

If $\xi_i : [0, \tau_{\max}) \rightarrow E$ is maximally defined solution of (1) such that $\xi_i(0) > 0$ for $i = 1, \dots, N$ then

- (i) $\xi_i(t) > 0$ for $i = 1, \dots, N$, $t \in [0, \tau_{\max})$,
- (ii) $\tau_{\max} = \infty$,
- (iii) $\limsup_{t \rightarrow \infty} \xi_i(t) \leq \frac{\rho_i \lambda_i + \bar{a}_i}{b_{ii}}$ for $i = 1, \dots, N$

Lemma 2

Assume (A2) - (A5). Then for any positive solution $u(t, x) = (u_1)(t, x), \dots, u_N(t, x)$ of the equation (D) there holds

$$u_i(t, x) \leq \xi_i(t) \varphi_i(x) \quad t \in [0, \tau_{\max}), \quad x \in \bar{\Omega}, \quad i = 1, \dots, N$$

where $\xi_i(t)$ is the solution of the IVP (1)

Lemma 3

Assume (A2) - (A5). Then for any maximally defined positive solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of (D) we have

(i) $\tau_{\max} = \infty$

(ii) $\limsup_{t \rightarrow \infty} u_i(t, x) \leq \frac{\rho_i \lambda_i + \bar{a}_i}{\underline{b}_{ii}}$, $i = 1, \dots, N$ where the limit is uniform in $x \in \bar{\Omega}$

(A6) There exist $\bar{b}_{ij} \geq 0$ such that $\frac{\partial f_i}{\partial u_j}(t, x, u) \geq -\bar{b}_{ij}$ for all $t \geq 0$, $x \in \bar{\Omega}$ $1 \leq i, j \leq N$, $u \in [0, \infty)^N$.

Averaging

Definition

We define a *lower average* of a function f_i as

$$m[f_i] := \liminf_{t-s \rightarrow \infty} \frac{1}{t-s} \int_s^t \min_{x \in \bar{\Omega}} f_i(\tau, x, 0, \dots, 0) d\tau$$

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$$(A7) \quad m[f_i] > 0.$$

Permanence in systems of PDEs with nonlocal dispersal

Definition

System (D) is *permanent* if there are positive constants $\underline{\delta}_i, \bar{\delta}_i > 0$ such that for each positive solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of (D) there holds

$$\underline{\delta}_i \leq \liminf_{t \rightarrow \infty} \frac{u_i(t, x)}{\varphi_i(x)} \leq \limsup_{t \rightarrow \infty} \frac{u_i(t, x)}{\varphi_i(x)} \leq \bar{\delta}_i \quad 1 \leq i \leq N$$

(permanence)

where the limit is uniform in $x \in \Omega$.

Average conditions for evolution system of (D)

$$m[f_i] > \rho_i \lambda_i + \sum_{\substack{j=1 \\ j \neq i}}^N \frac{\bar{b}_{ij}(M[f_j] + \rho_j \lambda_j)}{\underline{b}_{ij}} \quad 1 \leq i \leq N \quad (\text{A})$$

Theorem 1 [Main Theorem]

Assume **(A1)** through **(A7)**. If **(A)** holds then system **(D)** is permanent.

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- J. Balbus , *Permanence in nonautonomous competitive systems with nonlocal dispersal*, submitted for publication.

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The following result will be useful to prove Theorem 1.

Permanence in logistic equation of ODEs

Theorem 2 [Vance - Coddington Estimates]

Let $c: [t_0, \infty) \rightarrow \mathbb{R}$, where $t_0 \geq 0$, be a bounded continuous function, where $c_* > 0$ and $c^* > 0$ are such that $-c_* \leq c(t) \leq c^*$ for all $t \geq t_0$, and let $d > 0$. Assume moreover that there are $L > 0$ and $\beta > 0$ such that

$$\frac{1}{L} \int_t^{t+L} c(\tau) d\tau \geq \beta$$

for all $t \geq t_0$.

Theorem 2 [Vance - Coddington Estimates] continued

Then for any solution $\zeta(t)$ of the initial value problem

$$\begin{cases} \zeta' = (c(t) - d\zeta)\zeta \\ \zeta(t_0) = \zeta_0, \end{cases}$$

where $\zeta_0 > 0$, there holds

$$\frac{\beta}{d} e^{-L(c_* + \beta)} \leq \liminf_{t \rightarrow \infty} \zeta(t) \leq \limsup_{t \rightarrow \infty} \zeta(t) \leq \frac{c^*}{d}. \quad (\text{permanence-logistic})$$

Theorem 2 [Vance - Coddington Estimates] continued

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- R. R. Vance and E. A. Coddington, *A nonautonomous model of population growth*, J. Math. Biol. **27** (1989), no. 5, 491–506.

proof of Theorem 1

The right-hand side of the inequality (permanence) is satisfied by Lemma 3 (ii). Fix a positive solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of system (D). Let $\xi_i(t)$, $1 \leq i \leq N$, $t \geq 0$, be the solutions of (1). Fix $1 \leq i \leq N$.

sketch of the proof of Theorem 1 [continued]

Let $\eta_i(t)$, $t \geq t_0$, be the positive solution of the following problem

$$\begin{cases} \eta_i'(t) = (\rho_i \lambda_i + \min_{x \in \bar{\Omega}} f_i(t, x, 0, \dots, 0) - \bar{b}_{ii} \eta_i - \sum_{\substack{j=1 \\ j \neq i}}^N \bar{b}_{ij} \xi_j(t)) \eta_i(t) \\ \eta_i(t_0) = \inf_{x \in \Omega} \frac{u_i(t_0, x)}{\varphi_i(x)}. \end{cases}$$

It is easy to see that $u_i(t, x) \geq \eta_i(t) \varphi_i(x)$ for all $t \geq t_0$ and $x \in \bar{\Omega}$.

sketch of the proof of Theorem 1 [continued]

Now we apply Theorem 2 to (D) where

$$c(t) = \min_{x \in \bar{\Omega}} f_i(t, x, 0, \dots, 0) - \lambda_i \mu_i - \sum_{\substack{j=1 \\ j \neq i}}^N \bar{b}_{ij}(\varepsilon_0) \xi_j(t) \quad i \quad d = \bar{b}_{ii}(\varepsilon_0).$$

sketch of the proof Theorem 1 [continued]

To prove the permanence of system (D) we show that the parameters in Theorem 1 do not depend on the solution $u(t, x)$, for sufficiently large t . □

Practical persistence

Now we replace conditions (A) with

$$m[f_i] > \rho_i \lambda_i + \sum_{\substack{j=1 \\ j \neq i}}^N \frac{\bar{b}_{ij}(\bar{a}_j + \rho_i \lambda_j)}{\underline{b}_{jj}}$$

Then we can give the lower estimates on the numbers δ_i (in the definition of permanence) in terms of the parameters of system (D):

$$\delta_i \geq \frac{\beta}{\underline{b}_{ii}} \exp(-L(m[f_i] - \underline{a}_i)).$$

System with nonlocal dispersal in habitats with non-flux boundary

In this section we consider the competition system with nonlocal dispersal in environments with non - flux boundary

$$\frac{\partial u_i}{\partial t} = \rho_i \int_{\Omega} K_i(x, y)[u_i(t, y) - u_i(t, x)]dy + f_i(t, x, u_1, \dots, u_N)u_i,$$
$$t \geq 0, x \in \bar{\Omega}, i = 1, \dots, N.$$

(DN)

Note that system (DN) is the nonlocal dispersal counterpart of the following Kolmogorov competing system with random dispersal and Neumann boundary conditions

$$\begin{cases} \frac{\partial u_i}{\partial t} = -\rho_i \Delta u_i + f_i(t, x, u_1, \dots, u_N)u_i & t \geq 0, x \in \Omega \\ \frac{\partial u_i}{\partial n} = 0 & x \in \partial\Omega. \end{cases}$$

We note that principal eigenvalue of the nonlocal dispersal operator on domain with nonflux boundary

$$\begin{cases} \int_{\Omega} K_i(x, y)(\varphi_i(x) - \varphi_i(y))dy = \lambda\varphi(x) & \text{on } \Omega \\ \frac{\partial u_i}{\partial n} = 0 & \text{on } \partial\Omega \end{cases}$$

is zero.

Definition

System (DN) is *permanent* if there are positive constants $\underline{\delta}_i, \bar{\delta}_i > 0$ such that for each positive solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of (DN) there holds

$$\underline{\delta}_i \leq \liminf_{t \rightarrow \infty} u_i(t, x) \leq \limsup_{t \rightarrow \infty} u_i(t, x) \leq \bar{\delta}_i \quad 1 \leq i \leq N$$

where the limit is uniform in $x \in \Omega$.

Average conditions for evolution system of (DN)

$$m[f_i] > \sum_{\substack{j=1 \\ j \neq i}}^N \frac{\bar{b}_{ij} M[f_j]}{\underline{b}_{jj}}.$$

If for some $1 \leq i \leq N$ we assume the following stronger inequality

$$m[f_i] > \sum_{\substack{j=1 \\ j \neq i}}^N \frac{\bar{b}_{ij} \bar{a}_j}{\underline{b}_{jj}}$$

then we can give the lower estimates on the numbers δ_i in the terms of the parameters of system (DN)