

# Gradient estimates and global existence of smooth solutions to a system of reaction-diffusion equations with cross-diffusion

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# SKT cross-diffusion system

- Let  $\Omega \subset \mathbb{R}^n$  be open, smooth, bounded and  $n \geq 2$ . Consider the *Shigesada-Kawasaki-Teramoto* system of equations

$$\begin{cases} u_t = \Delta[(d_1 + a_{11}u + a_{12}v)u] + u(a_1 - b_1u - c_1v), \Omega \times (0, \infty), \\ v_t = \Delta[(d_2 + a_{21}u + a_{22}v)v] + v(a_2 - b_2u - c_2v), \Omega \times (0, \infty), \end{cases}$$

with **homogenous Newman boundary conditions** and

$$u(\cdot, 0) = u_0(\cdot) \geq 0, \quad v(\cdot, 0) = v_0(\cdot) \geq 0 \quad \text{in } \Omega.$$

- $u$  and  $v$  denote the population densities of two species.
- $d_k, a_k, b_k, c_k > 0$  and  $a_{ij} \geq 0$  are constants;
- $a_{11}, a_{22}$  are self-diffusion coefficients and  $a_{12}, a_{21}$  are cross-diffusion coefficients.

# Divergence form

- The PDE SKT system can be written as

$$\begin{cases} u_t = \nabla \cdot [(d_1 + 2a_{11}u + a_{12}v)\nabla u + a_{12}u\nabla v] + u(a_1 - b_1u - c_1v), \\ v_t = \nabla \cdot [(d_2 + a_{21}u + 2a_{22}v)\nabla v + a_{21}v\nabla u] + v(a_2 - b_2u - c_2v). \end{cases}$$

- In abstract form:

$$U_t = \nabla \cdot [J(U)\nabla U] + F(U),$$

where

$$U = \begin{pmatrix} u \\ v \end{pmatrix}, \quad J(U) = \begin{pmatrix} d_1 + 2a_{11}u + a_{12}v & a_{12}v \\ a_{21}u & d_2 + a_{21}u + 2a_{22}v \end{pmatrix},$$

and

$$F(U) = \begin{pmatrix} u(a_1 - b_1u - c_1v) \\ v(a_2 - b_2u - c_2v) \end{pmatrix}.$$

## Theorem (H. Amann, 1990)

Let  $r > n$  and  $u_0, v_0 \in W^{1,r}(\Omega)$  and non-negative. Then, there exists a *maximal existence time*  $T_{\max} > 0$  such that the SKT system has unique, local non-negative solution  $u, v$  with

$$u, v \in C([0, T_{\max}); W^{1,r}(\Omega)) \cap C^\infty(\bar{\Omega} \times (0, T_{\max})).$$

Moreover, if  $T_{\max} < \infty$  then

$$\lim_{t \rightarrow T_{\max}^-} \left[ \|u(\cdot, t)\|_{W^{1,r}(\Omega)} + \|v(\cdot, t)\|_{W^{1,r}(\Omega)} \right] = \infty.$$

# Global or finite time blow-up solution?

- The solution for the “full” STK system

$$\begin{cases} u_t = \Delta[(d_1 + a_{11}u + a_{12}v)u] + u(a_1 - b_1u - c_1v), \\ v_t = \Delta[(d_2 + a_{21}u + a_{22}v)v] + v(a_2 - b_2u - c_2v), \end{cases}$$

exists globally in time or has finite time blow up? **Very few results in very special cases.**

- We study the system when  $a_{21} = 0$ , that is

$$\begin{cases} u_t = \Delta[(d_1 + a_{11}u + a_{12}v)u] + u(a_1 - b_1u - c_1v), \\ v_t = \Delta[(d_2 + a_{22}v)v] + v(a_2 - b_2u - c_2v), \end{cases}$$

## Known results when $a_{21} = 0$

- For  $a_{11} > 0$ , the **SKT System**

$$\begin{cases} u_t = \Delta[(d_1 + a_{11}u + a_{12}v)u] & +u(a_1 - b_1u - c_1v), \\ v_t = \Delta[(d_2 + a_{22}v)v] & +v(a_2 - b_2u - c_2v), \end{cases}$$

with BC and initial data has global solution when  $n \leq 9$ .

- Y. Lou, W.-M. Ni and J. Wu (1998) for  $n = 2$  .
- D. Le, L. Nguyen, T. Nguyen (2004); Y. Choi, R. Lui, Y. Yamada (2003-2004:) for  $n \leq 5$ :
- T. P. (2008) for  $n \leq 9$ .
- Many other results: Restrictive conditions on the coefficients and initial data.

## Theorem (L. Hoang, T. Nguyen and T. P.)

Assume that  $a_{11} > 0$  and  $a_{21} = 0$ . Then for *any*  $n \geq 2$ , and non-negative  $u_0, v_0 \in W^{1,r}(\Omega)$  with  $r > n$ . Then, the solution  $(u, v)$  of the SKT system

$$\begin{cases} u_t = \Delta[(d_1 + a_{11}u + a_{12}v)u] & + u(a_1 - b_1u - c_1v), \\ v_t = \Delta[(d_2 + a_{22}v)v] & + v(a_2 - b_2u - c_2v), \end{cases}$$

(with B.C. and initial condition) *exists uniquely, globally in time solution and*

$$u, v \in \left[ C([0, \infty); W^{1,r}(\Omega)) \right] \cap \left[ C^\infty(\bar{\Omega} \times (0, \infty)) \right].$$

- Amann's theorem: Let  $T = t_{\max} > 0$  the maximal time existence of the local smooth solution.
- Assume  $T < \infty$ .
- We need to prove (for  $r > n$ ):

$$\lim_{t \rightarrow T^-} \left[ \|u(\cdot, t)\|_{W^{1,r}(\Omega)} + \|v(\cdot, t)\|_{W^{1,r}(\Omega)} \right] < \infty.$$

- Need to establish appropriate **a priori estimates** of the local solutions.



# Maximum Principle

- The PDE SKT system:

$$\begin{cases} u_t = \Delta[(d_1 + a_{11}u + a_{12}v)u] + u(a_1 - b_1u - c_1v), \\ v_t = \Delta[(d_2 + a_{22}v)v] + v(a_2 - b_2u - c_2v). \end{cases}$$

- The second equation can be written as

$$v_t = [d_2 + 2a_{22}v]\Delta v + 2a_{22}\nabla v \cdot \nabla v + v[a_2 - b_2u - c_2v]$$

- **Maximum Principle** implies (Lou-Ni-Wu, 98)

$$0 \leq v \leq \max \left\{ \sup_{\Omega} v_0(x), \frac{a_2}{c_2} \right\}.$$

- The first equation

$$\begin{aligned} u_t = [d_1 + 2a_{11}u + a_{12}v]\Delta u + [2a_{11}\nabla u + 2a_{12}\nabla v] \cdot \nabla u \\ + u[a_1 - b_1u - c_1v + a_{12}\Delta v] \end{aligned}$$

- M.P. only gives us  $u \geq 0$ . **Not upper bound of  $u$ .**

# Some simple a priori estimates

## Lemma (Lou-Ni-Wu, 98)

For fixed  $T > 0$ , let  $\Omega_T = \Omega \times [0, T]$ . Then, there exists  $C(T) > 0$  such that

$$\int_{\Omega} u(x, t) dx, \quad \int_{\Omega_T} u^2(x, t) dx dt \leq C(T).$$

## Proof.

- Note that the PDE of  $u$  is

$$u_t = \nabla \cdot [(d_1 + a_{12}v + 2a_{11}u)\nabla u + a_{12}u\nabla v] + u(a_1 - b_1u - c_1v), \quad \Omega_T.$$

- Also, the boundary condition give

$$\frac{\partial u}{\partial \vec{v}} = \frac{\partial v}{\partial \vec{v}} = 0, \quad \text{on } \partial\Omega \times (0, T).$$

- Then, the lemma follows by integrating the equation of  $u$ .

## Some simple estimates (cont.)

Lemma (Lou-Ni-Wu, 98)

*We also have*

$$\|v_t\|_{L^2(\Omega_T)} + \|\nabla v\|_{L^2(\Omega_T)} + \|\Delta v\|_{L^2(\Omega_T)} \leq C(T).$$

**Proof.**

Test the equation of  $v$

$$v_t = \Delta[(d_2 + a_{22}v)v] + v(a_2 - b_2u - c_2v)$$

with  $\Delta[(d_2 + a_{22}v)v]$ . □

# Energy estimates?

- The PDE of  $u$  is

$$u_t = \nabla \cdot [(d_1 + 2a_{11}u + a_{12}v)\nabla u + a_{12}u\nabla v] + u(a_1 - b_1u - c_1v).$$

- If we multiply the eqn with  $u$  and integrate

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{\Omega} u^2 + \int_{\Omega} (d_1 + 2a_{11}u + a_{12}v)|\nabla u|^2 \\ &= -a_{12} \int_{\Omega} u\nabla u\nabla v + \text{other terms.} \end{aligned}$$

- Note that we know  $u \in L^2$  and  $\nabla v = (d_2 + 2a_{22}v)^{-1}\nabla h \in L^2$ .
- It is therefore challenging to control  $\int_{\Omega} u\nabla u\nabla v$ . We need to understand the regularity of  $\nabla v$ .

# Key iteration lemma

- The PDE of  $u$ :

$$u_t = \nabla \cdot [(d_1 + 2a_{11}u + a_{12}v)\nabla u + a_{12}u\nabla v] + u(a_1 - b_1u - c_1v).$$

## Lemma

Let  $p > 2$  and assume that  $a_{11} > 0$ . Then for each

$$q \in \left[ p, \frac{p(n+1)}{(n+2-p)_+} \right] \quad \text{with } q \neq \infty,$$

we have

$$\|u\|_{L^q(\Omega_T)} \leq C(p, q, T)[1 + \|\nabla v\|_{L^p(\Omega_T)}].$$

- **Main task:** If  $u \in L^q(\Omega_T)$ , can we derive the estimate

$$\|\nabla v\|_{L^q(\Omega_T)} \leq C(q, p, T)[1 + \|u\|_{L^q(\Omega_T)}] \quad ?$$

# Known theory on gradient estimates

- Consider the linear PDE

$$w_t = \nabla \cdot [a(x, t)\nabla w] + \nabla \cdot F \quad \text{in } \Omega_T := \Omega \times (0, T)$$

- Calderón - Zygmund theory: We have

$$\|\nabla v\|_{L^p(\Omega_T)} \leq C[1 + \|F\|_{L^p(\Omega_T)}]$$

if (besides other conditions on data and  $\partial\Omega$ )

(i)  $a$  is uniformly elliptic, saying:  $1 \leq a(x, t) \leq 2$ , and

(ii) The oscillation of  $a(x, t)$  is small:

- Classical results require that  $a(x, t)$  is in  $C(\overline{\Omega_T})$ ;
- Recent developments require (2000s)

$$\|a\|_{BMO} \ll 1 \quad .$$

(L. Caffarelli; N. Krylov; G. Lieberman; S. Byun - L. Wang,...)

# Regularity problem

- The PDE of  $v$ :

$$v_t = \nabla \cdot \left[ \left\{ d_2 + 2a_{22}v(x, t) \right\} \nabla v \right] + v(a_2 - c_2 v) - b_2 uv, \quad \text{in } \Omega \times (0, T).$$

- We want to establish

$$\|\nabla v\|_{L^p(\Omega \times (0, T))} \leq C \left[ 1 + \|u\|_{L^p(\Omega \times (0, T))} \right].$$

- Difficulties:

(i) Main term  $a(x, t) := d_2 + 2a_{22}v(x, t)$  depends on solution.  
Therefore, its oscillation is not known to be small.

(ii) The equation is not invariant under either of the scalings

$$v(x, t) \rightarrow \frac{v(x, t)}{\lambda} \quad \text{or} \quad v(x, t) \rightarrow \frac{v(\theta x, \theta^2 t)}{\theta}, \quad \lambda, \theta > 0.$$

(iii) The equation is not invariant under the change of coordinates.

# Equations with scaling parameters

- Denote  $\Omega_T = \Omega \times (0, T)$ , we study the equation:

$$\begin{cases} w_t &= \nabla \cdot [(1 + \lambda \alpha w) \mathbf{A} \nabla w] + \theta^2 w(1 - \lambda w) - \lambda \theta c w & \text{in } \Omega_T, \\ \frac{\partial w}{\partial \vec{\nu}} &= 0 & \text{on } \partial\Omega \times (0, T), \\ w(\cdot, 0) &= w_0(\cdot) & \text{in } \Omega. \end{cases}$$

- Here,  $\theta, \lambda > 0$  and  $\alpha \geq 0$  are constants,
- $c(x, t)$  is a nonnegative measurable function,
- $\mathbf{A} = (a_{ij}) : \Omega_T \rightarrow \mathcal{M}^{n \times n}$  is symmetric, measurable and  $\exists \Lambda > 0$  such that

$$\Lambda^{-1} |\xi|^2 \leq \xi^T \mathbf{A}(x, t) \xi \leq \Lambda |\xi|^2 \quad \text{for a.e. } (x, t) \in \Omega_T \text{ and for all } \xi \in \mathbb{R}^n.$$



- Let  $w$  be a solution of the PDE

$$w_t = \nabla \cdot [(1 + \lambda \alpha w) \mathbf{A} \nabla w] + \theta^2 w(1 - \lambda w) - \lambda \theta c w.$$

- Then, for  $M > 0$ , we see that  $w_1 = w/M$  solves

$$\partial_t w_1 = \nabla \cdot [(1 + \lambda_1 \alpha w_1) \mathbf{A} \nabla w_1] + \theta^2 w_1(1 - \lambda_1 w_1) - \lambda_1 \theta c_1 w_1.$$

with

$$\lambda_1 = \lambda M, \quad c_1(x, t) = c(x, t)/M.$$

- Also, for  $r > 0$ ,  $w_2(x, t) = w(rx, r^2t)/r$  solves

$$\partial_t w_2 = \nabla \cdot [(1 + \lambda_2 \alpha w_2) \mathbf{A}_2 \nabla w_2] + \theta_2^2 w_2(1 - \lambda_2 w_2) - \lambda_2 \theta_2 c_2 w_2.$$

with

$$\lambda_2 = \lambda r, \quad \theta_2 = \theta r, \quad c_2(x, t) = c(rx, r^2t), \quad \mathbf{A}_2(x, t) = \mathbf{A}(rx, r^2t).$$

Theorem (L. Hoang, T. Nguyen and T. P.)

Let  $p > 2$ . Then there exists a number  $\delta = \delta(p, \Lambda, n, \alpha) > 0$  such that if  $\Omega$  is a Lipschitz domain with the Lipschitz constant  $\leq \delta$  and  $[\mathbf{A}]_{BMO(\Omega_T)} \leq \delta$ , then for any weak solution  $w$  of

$$\begin{cases} w_t &= \nabla \cdot [(1 + \lambda \alpha w) \mathbf{A} \nabla w] + \theta^2 w(1 - \lambda w) - \lambda \theta c w & \text{in } \Omega_T, \\ \frac{\partial w}{\partial \vec{\nu}} &= 0 & \text{on } \partial\Omega \times (0, T), \\ w(\cdot, 0) &= w_0(\cdot) & \text{in } \Omega. \end{cases}$$

satisfying  $0 \leq w \leq \lambda^{-1}$  in  $\Omega_T$ , we have

$$\int_{\Omega \times [\bar{t}, T]} |\nabla w|^p \, dx dt \leq C \left\{ \left( \frac{\theta}{\lambda} \vee \|w\|_{L^2(\Omega_T)} \right)^p + \int_{\Omega_T} |c|^p \, dx dt \right\}$$

for every  $\bar{t} \in (0, T)$ . Here  $C > 0$  is a constant depending only on  $\Omega$ ,  $\bar{t}$ ,  $p$ ,  $\Lambda$ ,  $\alpha$  and  $n$  and independent of  $\theta, \lambda$ .

# Main ideas (interior estimates)

- PERTURBATION TECHNIQUE(Caffarelli–Peral): Comparing the solution of

$$w_t = \nabla \cdot [(1 + \lambda\alpha w)\mathbf{A}\nabla w] + \theta^2 w(1 - \lambda w) - \lambda\theta c w \quad \text{in } Q_6 \quad (1)$$

with that of the reference equation

$$h_t = \nabla \cdot [(1 + \lambda\alpha h)\bar{\mathbf{A}}_{B_4}(t)\nabla h] + \theta^2 h(1 - \lambda h) \quad \text{in } Q_4, \quad (2)$$

where  $\bar{\mathbf{A}}_{B_4}(t)$  is the average of  $\mathbf{A}(\cdot, t)$  over  $B_4$ , that is,

$$\bar{\mathbf{A}}_{B_4}(t) := \frac{1}{|B_4|} \int_{B_4} \mathbf{A}(x, t) dx.$$

- **Key idea:** Use the regularity of  $h$  to obtain the regularity of  $w$  when  $w$  is sufficiently "close to"  $h$ .
- Here,  $Q_r$  denotes the parabolic cylinder of radius  $r$ .

# Regularity of solutions for the reference equation

## Lemma ( De Giorgi - Nash - Moser)

There exists a constant  $C = C(n, \Lambda, \alpha)$  such that every  $\lambda > 0$  and every weak solution  $0 \leq h \leq \lambda^{-1}$  solution of

$$h_t = \nabla \cdot [(1 + \lambda \alpha h) \bar{A}_{B_4}(t) \nabla h] + \theta^2 h(1 - \lambda h) \quad \text{in } Q_4,$$

we have

$$\|\nabla h\|_{L^\infty(Q_3)}^2 \leq C(n, \Lambda, \alpha) \frac{1}{|Q_4|} \int_{Q_4} |\nabla h|^2 dxdt.$$

**Note:** The constant  $C$  is independent on  $\lambda$ .

# Approximation lemma

## Lemma

For any  $\varepsilon > 0$ , there exists  $\delta = \delta(\varepsilon, n, \Lambda, \alpha) > 0$  such that for all  $\theta, \lambda > 0$ , and  $0 < r \leq 1$ , if

$$\frac{1}{|Q_{4r}|} \int_{Q_{4r}} \left[ |\mathbf{A}(x, t) - \bar{\mathbf{A}}_{B_{4r}}(t)|^2 + |c(x, t)|^2 \right] dxdt \leq \delta,$$

then for any weak solution  $w$  of (1) in  $Q_{5r}$  satisfying

$$0 \leq w \leq \lambda^{-1} \text{ in } Q_{4r}, \quad \text{and} \quad \frac{1}{|Q_{4r}|} \int_{Q_{4r}} |\nabla w|^2 dxdt \leq 1,$$

and weak solution  $h$  of (2) in  $Q_{4r}$  satisfying  $h = w$  on  $\partial_p Q_{4r}$ , we have

$$\frac{1}{|Q_{4r}|} \int_{Q_{4r}} |w - h|^2 dxdt \leq \varepsilon r^2 \quad \text{and} \quad \frac{1}{|Q_{4r}|} \int_{Q_{2r}} |\nabla w - \nabla h|^2 dxdt \leq \varepsilon.$$

# Decay estimate of distribution of maximal function

## Proposition

Assume  $c \in L^2(Q_6)$ .  $\exists N = N(n, \Lambda, \alpha) > 1$  such that for any  $\varepsilon > 0$ , we can find  $\delta = \delta(\varepsilon, n, \Lambda) > 0$  such that if

$$\sup_{0 < \rho \leq 4} \sup_{(y, s) \in Q_1} \frac{1}{|Q_\rho(y, s)|} \int_{Q_\rho(y, s)} |\mathbf{A}(x, t) - \bar{\mathbf{A}}_{B_\rho(y)}(t)|^2 dx dt \leq \delta,$$

then for any weak solution  $w$  of (1) satisfying

$$0 \leq w \leq \lambda^{-1} \quad \text{in } Q_5, \quad \text{and} \quad |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > N\}| \leq \varepsilon |Q_1|,$$

we have

$$\begin{aligned} & |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > N\}| \\ & \leq (10)^{n+2} \varepsilon \left\{ |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > 1\}| + |\{Q_1 : \mathcal{M}_{Q_5}(c^2) > \delta\}| \right\}. \end{aligned}$$

# Finishing the proof - Step I

- Assume for a moment that

$$|\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > N\}| \leq \varepsilon |Q_1|.$$

- Then, by the Proposition (for  $\varepsilon_1 = (10)^{n+2}\varepsilon$ )

$$\begin{aligned} & |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > N\}| \\ & \leq \varepsilon_1 \left\{ |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > 1\}| + |\{Q_1 : \mathcal{M}_{Q_5}(c^2) > \delta\}| \right\}. \end{aligned}$$

- Iteration: At the step  $k^{\text{th}}$ , we use the scaling

$$w \rightarrow w_k := w / \sqrt{N^k}, \quad k = 1, 2, \dots,$$

we eventually obtain

$$\begin{aligned} & |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla u|^2) > N^k\}| \\ & \leq \varepsilon_1^k |\{Q_1 : \mathcal{M}_{Q_5}(|\nabla u|^2) > 1\}| + \sum_{i=1}^k \varepsilon_1^i |\{Q_1 : \mathcal{M}_{Q_5}(c^2) > \delta N^{k-i}\}| \end{aligned}$$

- This gives the estimate of  $\|\nabla w\|_{L^p(Q_1)}$ .

# Finishing the proof - Step II

- Step 2: To remove the assumption in Step 1, we just use the weak type 1 – 1 estimate:

$$|\{Q_1 : \mathcal{M}_{Q_5}(|\nabla w|^2) > NM^2\}| \leq \frac{C}{NM^2} \int_{Q_5} |\nabla w|^2 dxdt.$$

- By the appropriate choice of  $M$ , we can obtain with  $\bar{w} = w/M$

$$|\{Q_1 : \mathcal{M}_{Q_5}(|\nabla \bar{w}|^2) > N\}| \leq \varepsilon |Q_1|.$$

- Since  $\bar{w}$  is a weak solution, we can apply the Step I for  $\bar{w}$ , to derive  $\|\nabla \bar{w}\|_{L^p(Q_1)}$ .
- Then we can derive the estimate of  $\|\nabla w\|_{L^p(Q_1)}$ .



THANK YOU FOR YOUR ATTENTION