

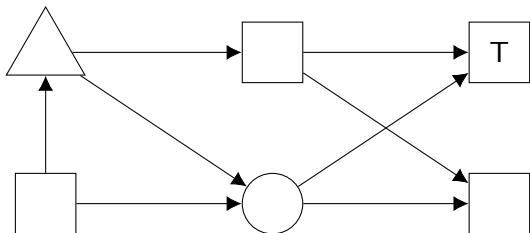
A Tour of the Complexity Classes Between P and NP

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Joint work with Spencer Gordon, Ruta Mehta, Rahul Savani

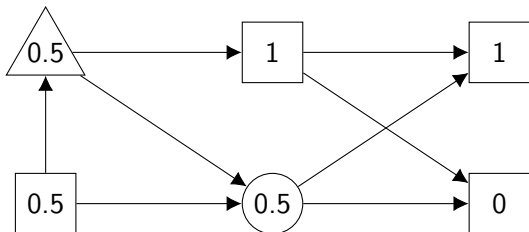
Simple stochastic games



A two player game

- ▶ Maximizer (box) wants to reach T
- ▶ Minimizer (triangle) who wants to avoid T
- ▶ Nature (circle) plays uniformly at random

Simple stochastic games

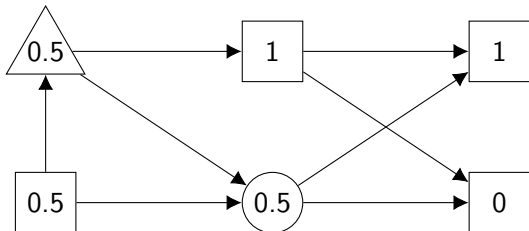


Value of a vertex:

- ▶ The largest probability of winning that max can ensure
- ▶ The smallest probability of winning that min can ensure

Computational Problem: find the value of each vertex

Simple stochastic games

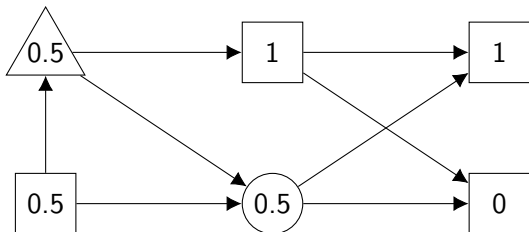


Is the problem

- ▶ **Easy?** Does it have a polynomial time algorithm?
- ▶ **Hard?** Perhaps no such algorithm exists

This is currently unresolved

Simple stochastic games



The problem lies in $NP \cap \text{co-NP}$

- ▶ So it is unlikely to be NP-hard

But there are a lot of **NP-intermediate** classes...

Simple stochastic games

Solving a simple-stochastic game lies in

$NP \cap co-NP \cap UP \cap co-UP \cap TFNP \cap$

$PPP \cap PPA \cap PPAD \cap PLS \cap$

$CLS \cap EOPL \cap UEOPL$

Simple stochastic games

Solving a simple-stochastic game lies in

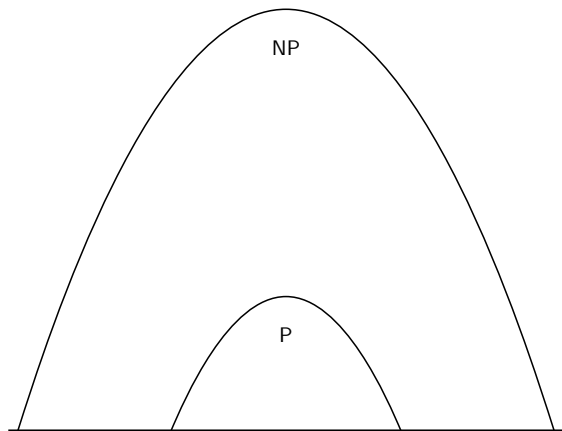
NP \cap co-NP \cap UP \cap co-UP \cap **TFNP** \cap

PPP \cap PPA \cap **PPAD** \cap **PLS** \cap

CLS \cap **EOPL** \cap **UEOPL**

This talk: where are these complexity classes?

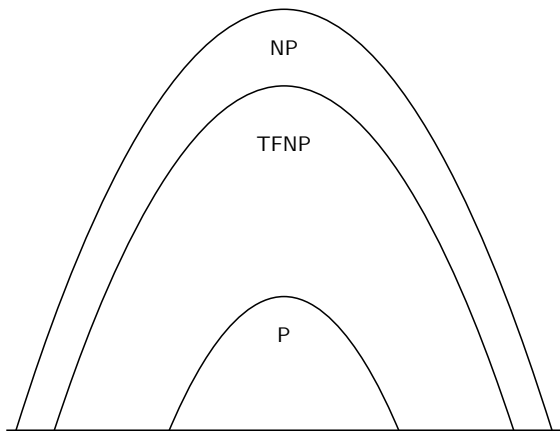
Complexity classes between P and NP



There are many problems that lie **between** P and NP

- ▶ Factoring, graph isomorphism, computing Nash equilibria, local max cut, simple-stochastic games, ...

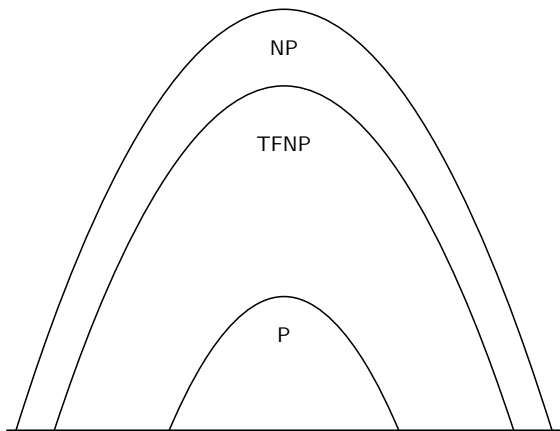
Complexity classes between P and NP



FNP is the class of **function** problems in NP

- ▶ Given polynomial time computable relation R and value x
- ▶ Find y such that $(x, y) \in R$

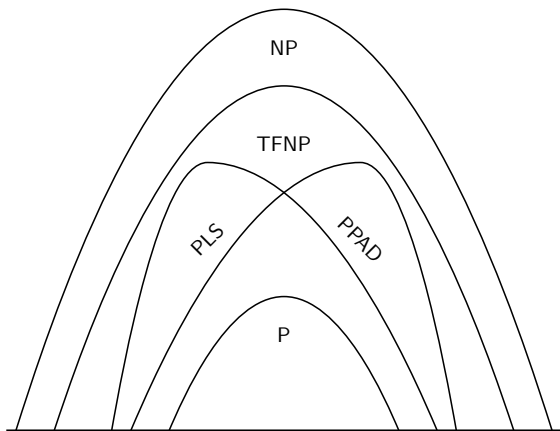
Complexity classes between P and NP



TFNP is the subclass of problems that **always** have solutions

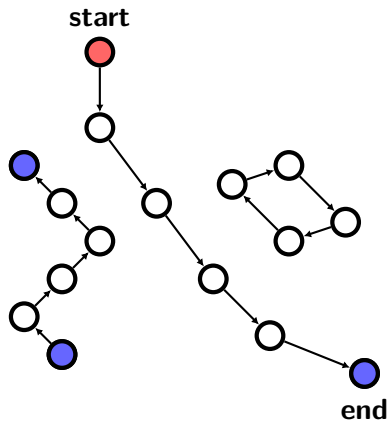
- ▶ Contains factoring, Nash equilibria, local max cut, simple-stochastic games, ...

Complexity classes between P and NP



PPAD and PLS are two **subclasses** of TFNP

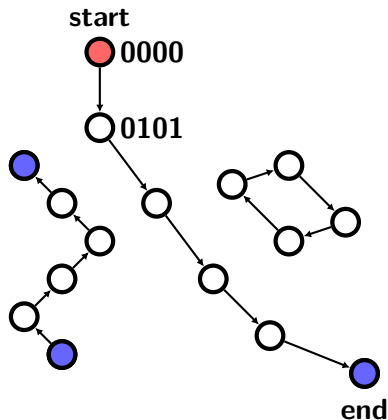
PPAD (Papadimitriou 1994)



End-of-the-Line:

Given a graph G of in/out degree at most 1 and a **source start** vertex
find another vertex of degree 1

PPAD (Papadimitriou 1994)



Catch:

The graph is **exponentially large**

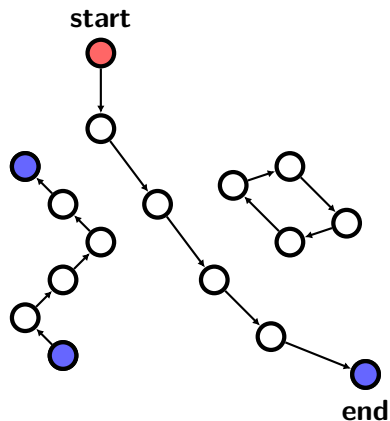
It is defined by

- ▶ A circuit S that gives a successor
- ▶ A circuit P that gives a predecessor

$$S(0000) = 0101$$

$$P(0101) = 0000$$

PPAD (Papadimitriou 1994)

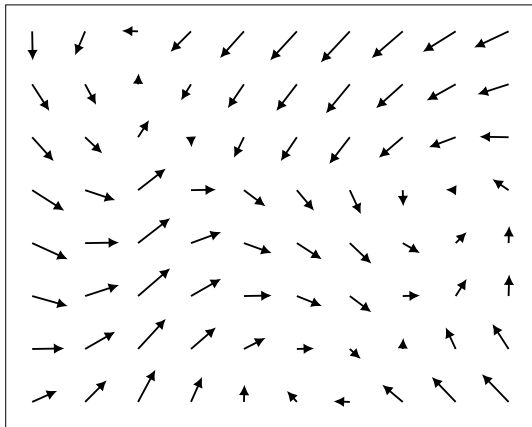


A problem is in PPAD if it can be reduced to EOTL

A problem is **PPAD-hard** if EOTL can be reduced to it

- ▶ Convincing evidence of hardness?

Brouwer: A PPAD-complete problem



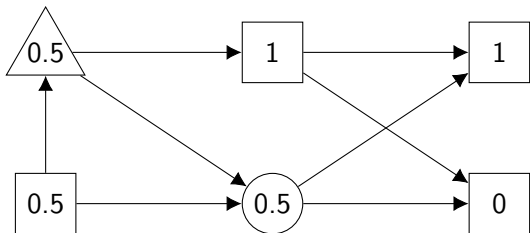
Given a continuous function $f : [0, 1]^n \rightarrow [0, 1]^n$

- ▶ find a **fixpoint**: a point x such that $f(x) = x$

PPAD-complete problems

- ▶ computing mixed equilibria in games
- ▶ computing Brouwer fixed points
- ▶ computing market equilibria

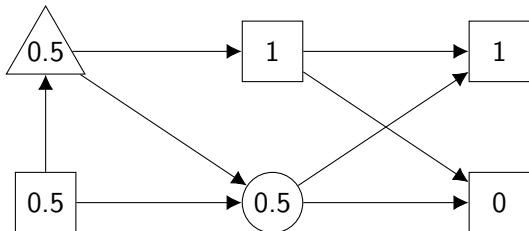
Simple stochastic games are in PPAD



The vertex values satisfy **optimality equations**

$$f(v) = \begin{cases} 1 & \text{if } v \text{ is the target} \\ 0 & \text{if } v \text{ is any other sink} \\ \max(u, w) & \text{if } v \text{ is a max vertex with successors } u \text{ and } w \\ \min(u, w) & \text{if } v \text{ is a min vertex with successors } u \text{ and } w \\ (u + w)/2 & \text{if } v \text{ is a random vertex with successors } u \text{ and } w \end{cases}$$

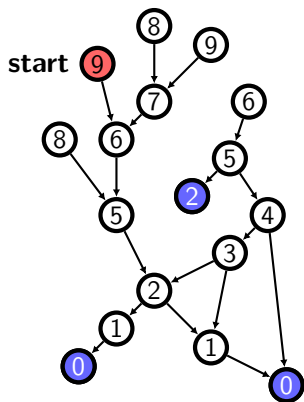
Simple stochastic games are in PPAD



$f: [0, 1]^n \rightarrow [0, 1]^n$ is a Brouwer function

When the game is **stopping**, the fixpoint of f gives the values for each vertex (Condon 1992)

Polynomial Local Search (PLS)



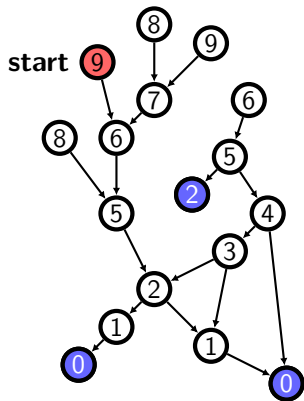
Given

- ▶ a DAG
- ▶ a starting vertex

Find

- ▶ a sink vertex

Polynomial Local Search (PLS)



Catch:

The graph is **exponentially large**

Defined by

- ▶ A circuit S giving the successor vertices
- ▶ A circuit p giving a **potential**

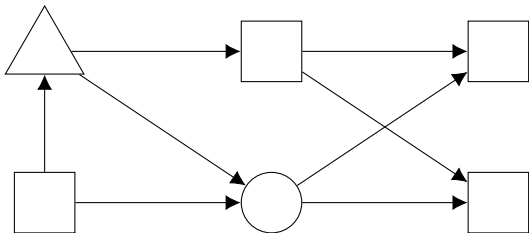
Every edge decreases the potential

$$p(S(v)) < p(v)$$

PLS-complete problems:

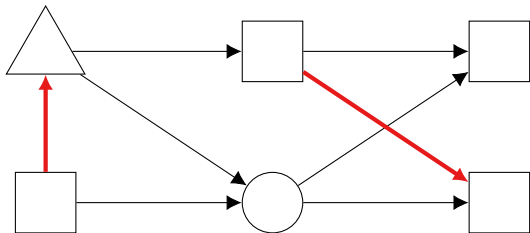
- ▶ local max cut
- ▶ computing pure equilibria in congestion games
- ▶ computing stable outcomes in hedonic games

Simple stochastic games are in PLS



A **strategy improvement** algorithm puts SSGs in PLS

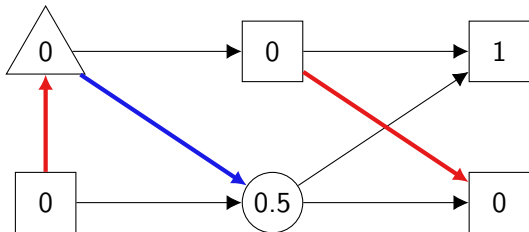
Simple stochastic games are in PLS



A **strategy improvement** algorithm puts SSGs in PLS

1. Maximizer picks a positional strategy

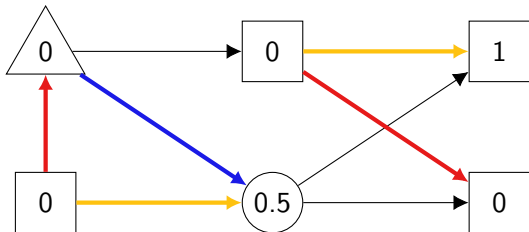
Simple stochastic games are in PLS



A **strategy improvement** algorithm puts SSGs in PLS

1. Maximizer picks a positional strategy
2. Compute a best response for the Minimizer

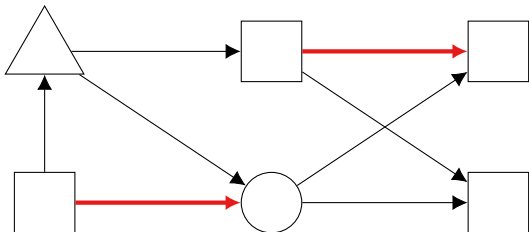
Simple stochastic games are in PLS



A **strategy improvement** algorithm puts SSGs in PLS

1. Maximizer picks a positional strategy
2. Compute a best response for the Minimizer
3. Determine switchable edges for Maximizer

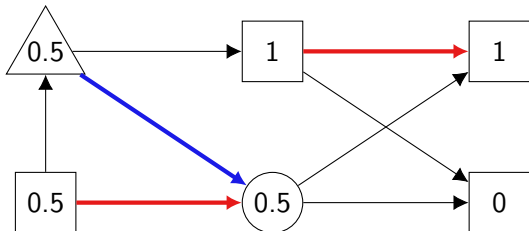
Simple stochastic games are in PLS



A **strategy improvement** algorithm puts SSGs in PLS

1. Maximizer picks a positional strategy
2. Compute a best response for the Minimizer
3. Determine switchable edges for Maximizer
4. Switch some switchable edges

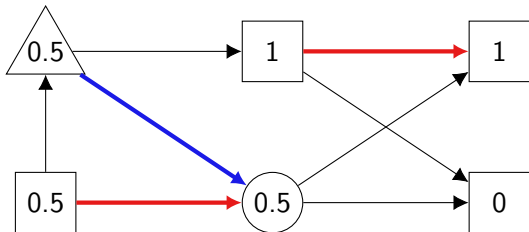
Simple stochastic games are in PLS



A **strategy improvement** algorithm puts SSGs in PLS

1. Maximizer picks a positional strategy
2. Compute a best response for the Minimizer
3. Determine switchable edges for Maximizer
4. Switch some switchable edges
5. Compute a new best response

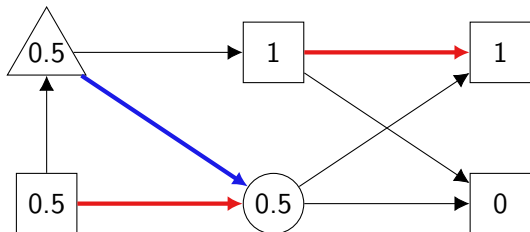
Simple stochastic games are in PLS



After switching any subset of switchable edges

- ▶ No vertex decreases in value
- ▶ At least one vertex **strictly increases** in value

Simple stochastic games are in PLS



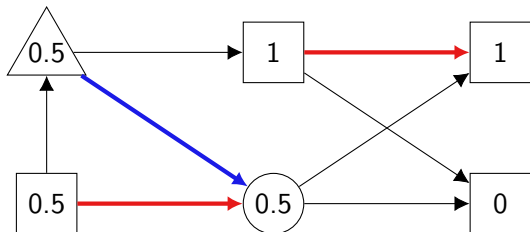
After switching any subset of switchable edges

- ▶ No vertex decreases in value
- ▶ At least one vertex **strictly increases** in value

If a Maximizer strategy has **no switchable edges**

- ▶ We have found the value of all vertices

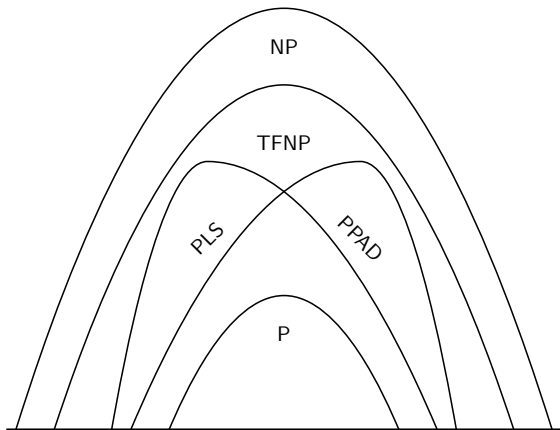
Simple stochastic games are in PLS



This puts simple-stochastic games **in PLS**

- ▶ A vertex of the DAG is a strategy for Max
- ▶ The neighbors are all strategies that can be switched to
- ▶ The potential is the sum of the values

Complexity classes between P and NP



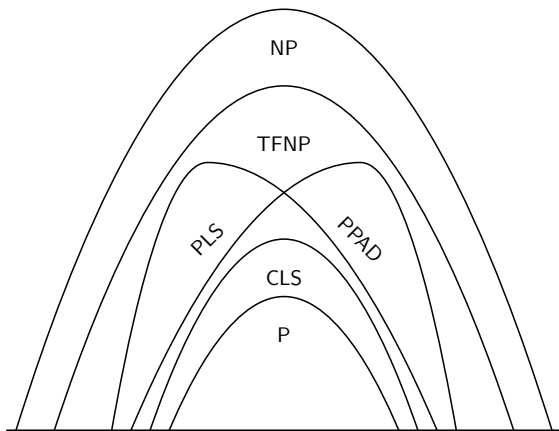
Are there any other interesting problems in PPAD and PLS?

Are there any other interesting problems in PPAD and PLS?

Yes!

1. Solving a Simple Stochastic Game
2. Finding a mixed NE of a Team Polymatrix Game
3. Finding a mixed NE of a Congestion Game
4. Solving a P-matrix Linear Complementarity Problem
5. Finding a fixed point of a Contraction Map
6. Solving reachability on a switching network
7. ...

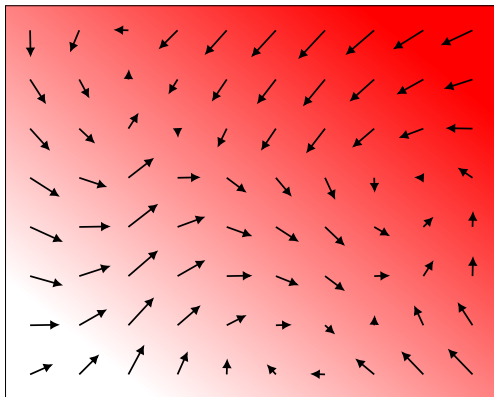
Complexity classes between P and NP



CLS was defined to capture these problems

(Daskalakis and Papadimitriou, 2011)

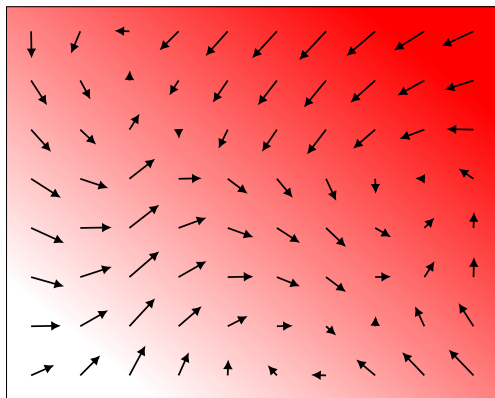
Continuous Local Search (CLS)



CLS is a Brouwer instance that **also** has a potential

- ▶ Continuous direction function $f : [0, 1]^3 \rightarrow [0, 1]^3$
- ▶ Continuous potential function $p : [0, 1]^3 \rightarrow [0, 1]$

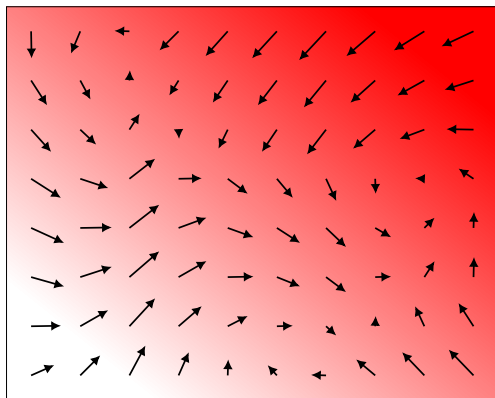
Continuous Local Search (CLS)



Find a point x where the potential **does not decrease**

$$p(f(x)) \geq p(x)$$

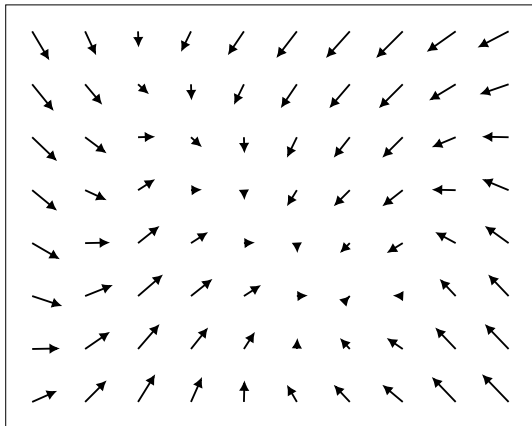
Continuous Local Search (CLS)



CLS contains **all** of the problems we saw on the previous slide

- ▶ It is now known to have **complete problems**
(Daskalakis, Tzamos, Zampetakis, 2018) (FGMS, 2017)

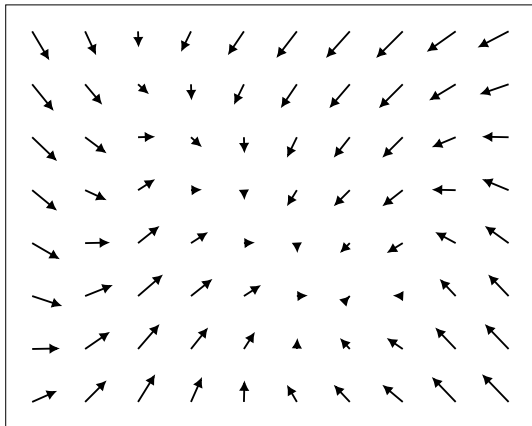
Contraction: a problem in CLS



f is **contracting** if

$$|f(x) - f(x')| \leq c \cdot |x - x'| \quad \text{for } c < 1$$

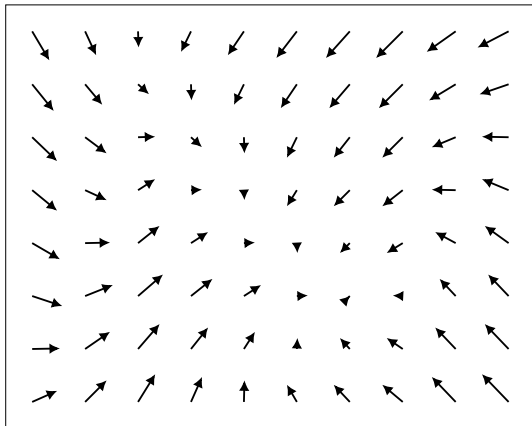
Contraction: a problem in CLS



Banach's fixpoint theorem

- ▶ Every contraction map has a **unique** fixpoint

Contraction: a problem in CLS

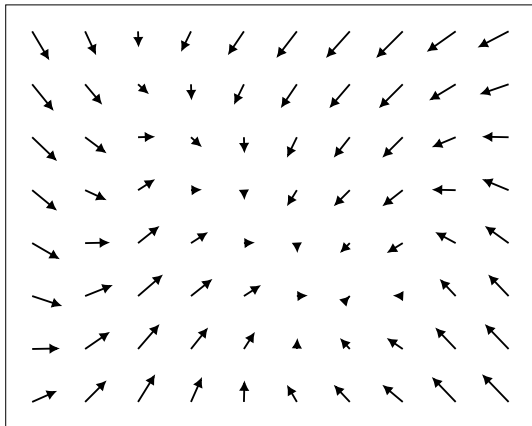


Problem: given a contraction map as an arithmetic circuit

- ▶ Find a **fixpoint** or a **violation** of contraction

No violations \Rightarrow the problem has a **unique** solution

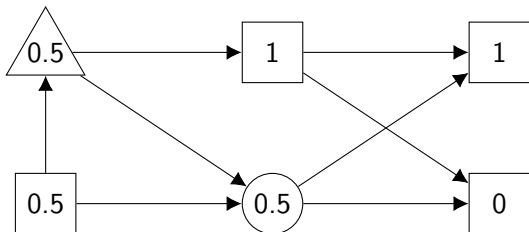
Contraction: a problem in CLS



Contraction is in CLS

- ▶ Direction function: f
- ▶ Potential function: $p(x) = |f(x) - x|$

Simple stochastic games are in CLS

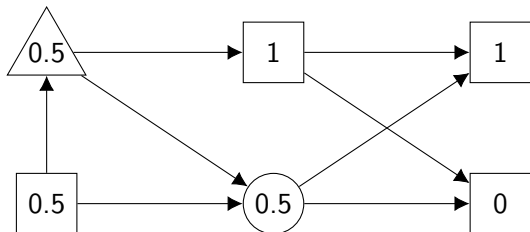


We can reduce SSG to contraction

- ▶ At each step **stop the game** with probability δ
- ▶ Otherwise continue

If δ is sufficiently small, the optimal values can be recovered

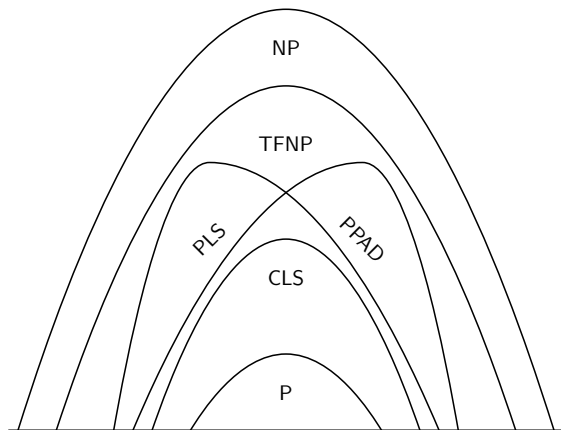
Simple stochastic games are in CLS



$$f(v) = \begin{cases} 1 & \text{if } v \text{ is the target} \\ 0 & \text{if } v \text{ is any other sink} \\ (1 - \delta) \cdot \max(u, w) & \text{if } v \text{ is a max vertex} \\ (1 - \delta) \cdot \min(u, w) & \text{if } v \text{ is a min vertex} \\ (1 - \delta) \cdot (u + w)/2 & \text{if } v \text{ is a random vertex} \end{cases}$$

f is contracting with $c = 1 - \delta$

Complexity classes between P and NP



Are we done?

- ▶ Will all of our problems be CLS-complete?

Is CLS a good complexity class?

Positives

- ▶ Contains lots of problems
- ▶ Has complete problems

Negatives

- ▶ Currently has no **natural** complete problems

Natural problem:

did anyone care about it before you showed it was complete?

Unique End of Potential Line

Do we expect all of the problems in CLS to be complete?

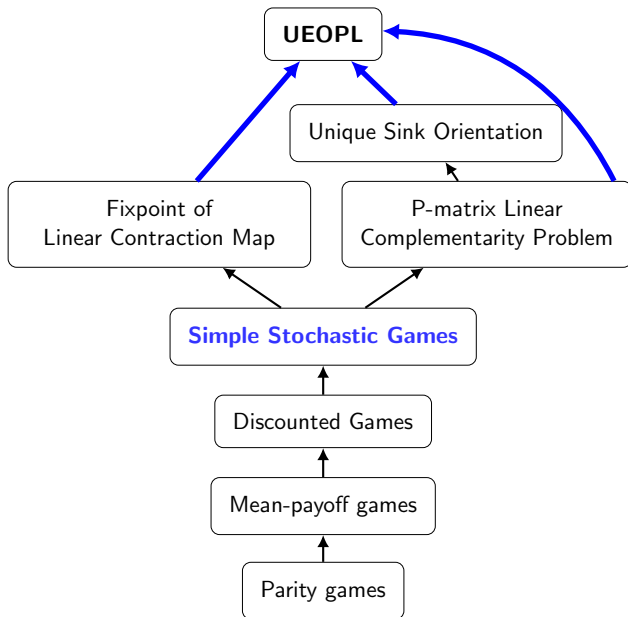
Our answer: **no!**

We identify a new class of problems **UEOPL** \subseteq CLS containing

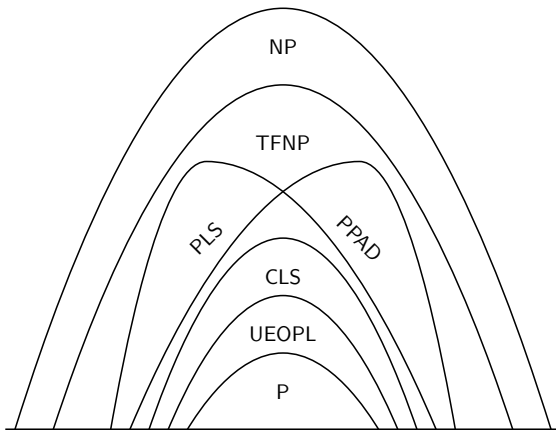
- ▶ Finding the fixpoint of a Linear Contraction Map
- ▶ Finding the sink of a Unique Sink Orientation
- ▶ Solving the P-matrix Linear Complementarity Problem

We believe that this is a **distinct** class of problems

Problems in UEOPL



Complexity classes between P and NP



UEOPL is the closest class to P among the subclasses of TFNP

Our **three problems**

- ▶ Contraction
- ▶ Unique sink orientation
- ▶ P-matrix LCP

Each can be formulated so that there are

- ▶ **proper solutions**
- ▶ **violation solutions**

When there are no **violations** there is a **unique** solution

UEOPL is intended to capture problems like this

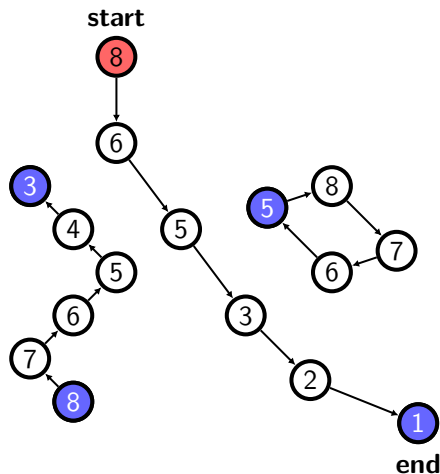
End of Potential Line (EOPL)

Combines the two **canonical** complete problems

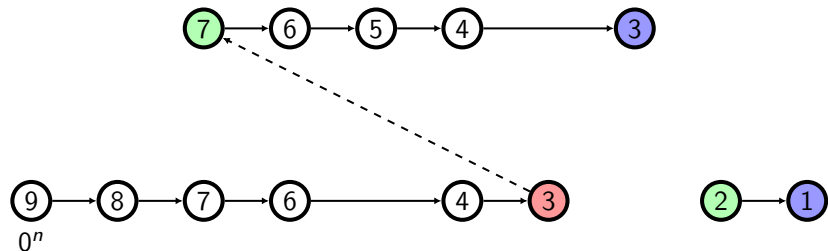
- ▶ An End-of-the-Line instance
- ▶ That has a potential

Find

- ▶ The end of a line
- ▶ A vertex where the potential increases



Unique End of Potential Line (UEOPL)

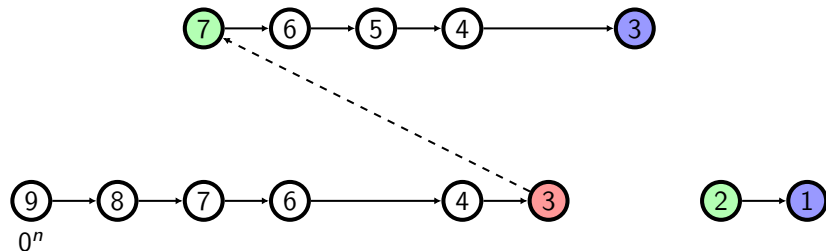


An EOPL instance with violations to make sure the line is unique

- ▶ Proper solution: The end of a line
- ▶ Violation 1: The start of a line other than 0^n
- ▶ Violation 2: An edge that increases the potential
- ▶ Violation 3: Any pair of vertices v and u satisfying

$$P(v) \geq P(u) > P(S(v))$$

Unique End of Potential Line (UEOPL)



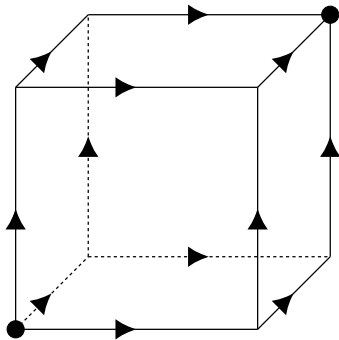
If there are no violations then there is a **unique** line

- ▶ That starts at 0^n
- ▶ And ends at the **unique** proper solution to the problem

Unique Sink Orientations of Cubes

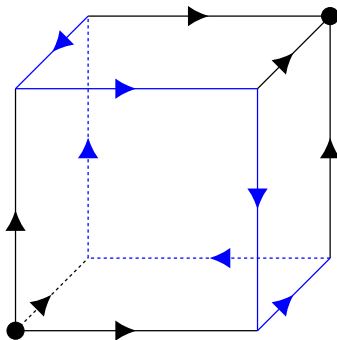
Orient the edges of an n -dimensional cube

- ▶ So that every face has a **unique** sink

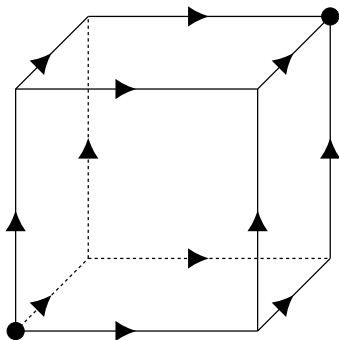


Unique Sink Orientations of Cubes

Can be **cyclic**:



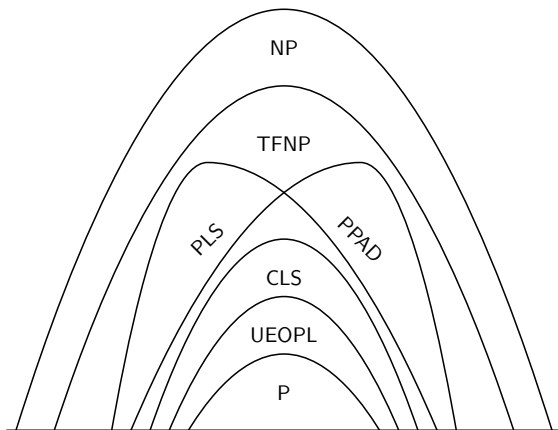
Unique Sink Orientations of Cubes



Simple-stochastic games reduce to **acyclic** USO

- ▶ The strategy improvement algorithm gives an AUSO
- ▶ Vertices are strategies
- ▶ The orientation is determined by the potential

Complexity classes between P and NP



Conjectures

- ▶ USO is complete for UEOPPL
- ▶ Contraction is complete for UEOPPL
- ▶ PLCP is complete for UEOPPL

Most of our algorithms for SSGs actually solve one of these problems

Simple-stochastic games are **not** complete for UEOPPL

SSGs are not a promise problem!

Open questions

What is the complexity of solving a simple stochastic game?

Is it **hard**?

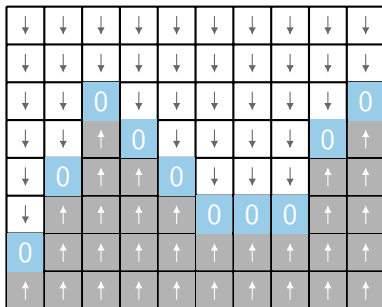
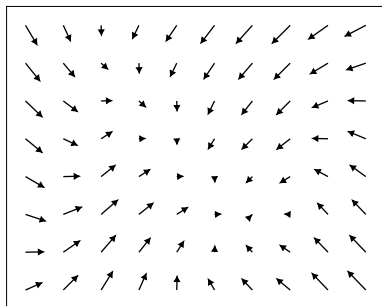
- ▶ Then what is the right class?

Is it **easy**?

- ▶ Then show me the algorithm!

Thanks!

Contraction to UEOPL



First we discretize the problem

- ▶ Lay a grid of points over the space
- ▶ For each dimension construct a **direction** function

Contraction to UEOPL

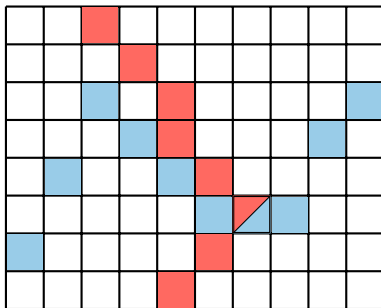
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↓	↓	↑	0	↓	↓	↓	↓	0	↑
↓	0	↑	↑	0	↓	↓	↓	↑	↑
↓	↑	↑	↑	↑	0	0	0	↑	↑
0	↑	↑	↑	↑	↑	↑	↑	↑	↑
↑	↑	↑	↑	↑	↑	↑	↑	↑	↑

→	→	0	←	←	←	←	←	←	←
→	→	→	0	←	←	←	←	←	←
→	→	→	→	0	←	←	←	←	←
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→	→	→	→	→	0	←	←	←	←
→	→	→	→	→	→	0	←	←	←
→	→	→	→	→	→	→	0	←	←
→	→	→	→	→	→	→	→	0	←
→	→	→	→	→	→	→	→	→	0

Discrete contraction

- ▶ Find a point that is 0 in all dimensions

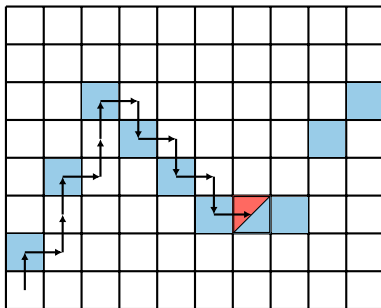
Contraction to UEOPL



A point is on the **surface** if it is 0 for some direction

- ▶ Every left/right slice has a unique point on the blue surface
- ▶ At each of these, we can follow the red direction function

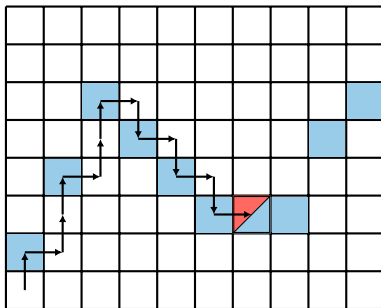
Contraction to UEOPL



The path

1. Start at (0,0)
2. Find the blue surface
3. Take one step in the red direction
4. If not at red surface, go to 2

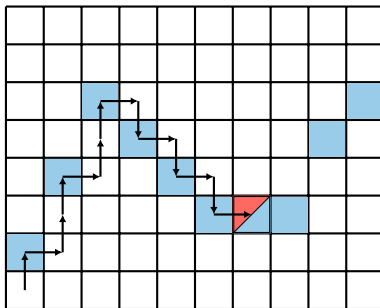
Contraction to UEOPPL



The potential

- ▶ The path never moves left
- ▶ In every slice, it either moves moves up or down

Contraction to UEOPL

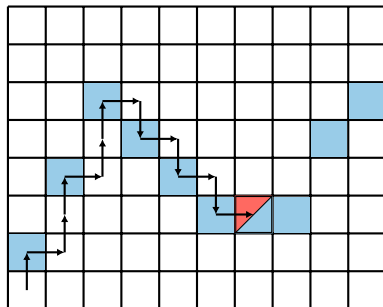


So we can use a pair (a, b) ordered lexicographically where

- ▶ a is the x coordinate of the vertex
- ▶ b is
 - ▶ y if we are moving up
 - ▶ $-y$ if we are moving down

This monotonically increases along the line

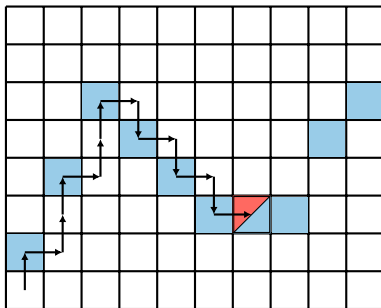
Contraction to UEOPL



Actually, this formulation only gives us a **forward** circuit

- ▶ But the line is unique
- ▶ So we can apply a technique of Hubáček and Yogev (2017) to make the line reversible

Contraction to UEOPL



Theorem

Contraction is in UEOPL